# **JUMO dTRANS T06**

in Mounting Rail Case in Accordance with Multifunctional Four-Wire-Transmitter DIN EN 61508 and EN ISO 13849



















3 8

(11)

> 3

ð

3.92

392.1 3.92





# Operating instructions

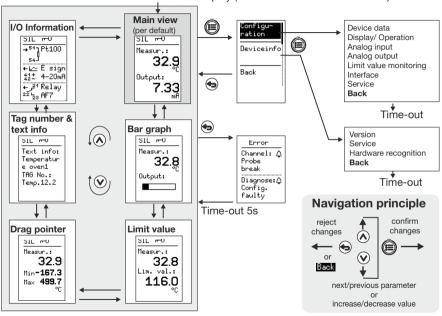
(translation of the German original manual)

70707100T90Z001K000

V5.00/EN/00690362/2020-06-30

# Operating overwiew

Normal display (12s after switch-on or Time-out)



	Operating overwiew	2
1	Brief description	10
1.1	Safety information	11
2	Identifying the device version	12
2.1	Scope of delivery	13
2.2	Accessories	14
2.3	Device software version, fabrication number	
2.4	Service addresses	14
3	Mounting	16
3.1	Dimensions	16
3.2	Mounting site, DIN-rail mounting	17
3.3	Close mounting	17
3.4	Dismounting	
3.5	Galvanic isolation	
3.6	Use of the USB interface	
4	Electrical connection	20
4.1	Installation notes	20
4.2	Connection diagram	21
1.2.1	Analog input (part of the safety channel)	
1.2.2	Analog output (part of the safety channel)	
1.2.3 1.2.4	Voltage supply (on the nameplate)	
5	Startun of the device	26

Display and control elements	26
Setting the display after device is switched on	26
Signal flow	29
Safety Manual	. 32
Validity of the safety manual	33
Special operating statuses	33
Issue of an error signal (safe state)	34
Relevant standards	34
Connection possibilities of the sensors	34
Terms and abbreviations according to DIN EN 61508 and DIN EN 61511	35
Safety-relevant parameters	38
Failure rates and SFF for 707071/X – 23/XXX (AC240V)	38
Failure rates and SSF for 707071/X – 29/XXX (DC24V).	38
Calculation of PFD avg	39
Determining the safety integrity level (SIL)	41
Safety integrity of the hardware	42
Safety-relevant system properties	43
Redundant use of the system	44
Sensor connection possibilities	45
Determining the achieved performance level PL	45
Terms and abbreviations according to standards series DIN EN ISO 13849	46
	Display and control elements.  Setting the display after device is switched on Extra code SIL Signal flow  Safety Manual Brief description, intended use Validity of the safety manual Special operating statuses. Behavior after a power failure During setup data transfer. After alteration of the configuration level (at the device or through setup) Issue of an error signal (safe state) Relevant standards Connection possibilities of the sensors Terms and abbreviations according to DIN EN 61508 and DIN EN 61511 Safety-relevant parameters. Failure rates and SFF for 707071/X – 23/XXX (AC240V). Failure rates and SFF for 707071/X – 29/XXX (DC24V). Calculation of PFD avg Determining the safety integrity level (SIL). Safety integrity of the hardware Safety-relevant system properties Redundant use of the system Sensor connection possibilities. Determining the achieved performance level PL Terms and abbreviations according to standards series DIN EN ISO 13849.

6.7.2	Calculations of the DIN EN ISO 13849-1 performance level – 707071/X - 23/XXX (AC240V)	
6.7.3	Calculations of the DIN EN ISO 13849-1 performance level – 707071/X - 29/XXX (DC24V)	
6.7.4	Risk reduction through the control system	
6.8	Other applicable device documentation	
6.9	Behavior during operation and in case of malfunction	
6.10	Regular tests	.49
6.10.1	Proof test A	
6.10.2	Proof test B	
6.10.3	Proof test C	
6.10.4	Recommended tests for temperature probes	57
7	Configuration	60
7.1	Overview	.60
7.2	Device data	.61
7.2.1	Language	61
7.2.2	Unit	61
7.2.3	Language after power on	61
7.3	Display/operation	.62
7.3.1	Normal display	62
7.3.2	Decimal place	62
7.3.3	Contrast	62
7.3.4	Lighting	63
7.3.5	Time-out lighting	63
7.3.6	Time-out operation	63
7.3.7	Code	63
7.4	Analog input	.64
7.4.1	Sensor type	64
7.4.2	Linearization	65

7.4.3	Temperature difference	.66
7.4.4	Temperature compens	.66
7.4.5	Resistance measuring range	.66
7.4.6	Line resistance	.66
7.4.7	Sensor factor	.66
7.4.8	Resistance Rx	.67
7.4.9	Line resistance RL	.67
7.4.10	Resistance R0	.67
7.4.11	Resistance RA, RS and RE	.68
7.4.12	Scaling start	.68
7.4.13	Scaling end	.68
7.4.14	Offset	.68
7.4.15	Fine calibration start actual.	.68
7.4.16	Fine calibration end actual	.68
7.4.17	Fine calibration start target	.68
7.4.18	Fine calibration end target.	.68
7.4.19	Noise suppression.	.68
7.5	Analog output	.69
7.5.1	Signal type.	.69
7.5.2	Output range start	.69
7.5.3	Output range end	.69
7.4.20	Filter time constant	.69
7.5.4	Scaling start	.70
7.5.5	Scaling end	.70
7.5.6	Reversion output	.70
7.5.7	Error signal	.70
7.5.8	Response for limit error	.70

7.5.9	Signal from diagnosis error	70
7.5.10	Simulation output	71
7.5.11	Simulation value	71
7.5.12	Behavior when leaving the scaling range	72
7.6	Limit value monitoring	73
7.6.1	Function.	73
7.7	RS485 interface	74
7.7.1	Baud rate	
7.6.2	Limit value	
7.6.3	Switch difference	74
7.6.4	Switching behavior	74
7.6.5	Switch on delay	74
7.6.6	Switch off delay	74
7.8	Service	75
7.8.1	Minimum meas. value	75
7.8.2	Maximum meas. value.	75
7.8.3	Min.value reset	75
7.8.4	Max.value reset	75
7.8.5	Switching cycle limit	75
7.7.2	Data format	75
7.7.3	Device address	75
7.8.6	Current switching cycles	76
8	Device info	. 77
8.1	Version	
8.2	Service	
8.2.1	Operating hours total	/8

8.2.2	Operating hours since last configuration	78
8.3	Hardware recognition	78
9	Technical data	80
9.1	Analog input	
9.1.1	RTD temperature probe.	
9.1.2	Thermocouples	
9.1.3	Standard signals	
9.1.4	Resistance transmitter	
9.1.5	Resistance/potentiometer	
9.2	Measuring circuit monitoring	
9.3	Test voltages	
9.4	Electrical safety	
9.5	Analog output	
9.6	Relay output (extra code 018)	
9.7	Display	
9.8	Electrical data	
9.9	Environmental influences	88
9.10	Housing	88
9.11	Approvals/approval marks	89
10	Setup program	90
10.1	Minimum hardware and software requirements:	
10.2	Displaying the device software version	
10.3	Forgotten the code?	
10.4	Customer-specific linearization	
10.5	Reset drag indicator	

10.6	Switch on / switch off SIL extra code	.93
10.7	Checking of safety relevant system settings	93
11	Error messages	. 94
11.1	Display types	.94
11.2	Safety channel	.95
11.3	Diagnostics channel	.97
11.4	Measured value recording	.99
12	What to do, if	100

 Certificates
 104

 SIL and PL
 104

13

13.1 13.2

13.3

# 1 Brief description

The transmitter acquires the temperature through an RTD temperature probe or a thermocouple (double thermocouple). The transmitter can also acquire standard signals such as .current 0(4) to 20 mA or voltage 0 to (1)10 V.

Additionally resistance transmitter with three-wire circuit, or resistance/potentiometer with two-wire/three-wire/four-wire circuit can be acquired.

The output signal is galvanically isolated from the measurement input and the voltage supply.

Depending on the measurement input, different linearization variants (linear, temperature-linear, customer-specific, etc.) are possible. Output signal: variants 0(4) to 20 mA and, alternatively, 0(2) to 10 V are available.

Process variables such as temperature or pressure are reliably emitted at the analog output and monitored for measuring overrange and underrange.

Type 707071 is functionally expandable through the extra code, relay output and an RS485 interface.

Visualization of measured values is accomplished using a dot-matrix LCD display with white backlight.

On the LCD display, it is possible to call up the connection diagram of the configured sensor input, signal output, as well as the optional relay and interface assignment.

If a malfunction occurs the transmitter sends a defined output signal according to the recommendation of NAMUR NE 43, which downstream systems can recognize.

The operating status is signaled optically using a two-color LED (red/green).

Smooth operation is indicated by a permanent green LED; malfunction statuses are indicated by a permanent red LED.

The sensor type, measuring range, linearization, output signal, limit values, etc. can be configured via setup program. Alternatively, configuration is also possible via four keys on the device.

Type 707071/8-XX-058 fulfills the requirements of SIL 2, or SIL 3 in redundant use, according to DIN EN 61508 and PL c/PL d according to DIN EN ISO 13849 as well as the requirements of DIN EN 60730-2-9.

The systematic suitability is defined at SC = 3 for HW and SW.

This means that SIL 2 or PL c for HFT = 0 (individual device) and SIL 3 or PL d for HFT = 1 (2 devices) is achieved.

The use of type 707071/8-XX-058 enables early and reliable detection of risks which could potentially result in personal injuries, environmental damage, or destruction of the production plant and production materials.

# 1.1 Safety information

Symbol	Meaning	Explanation
i	Important in- formation	This symbol refers to important information about the product, its handling, or additional benefits.
A	Danger	This symbol indicates that personal injury from electrocution may occur if the appropriate precautionary measures are not taken.
$\triangle$	Caution	This symbol in connection with the signal word indicates that <b>material damage</b> or <b>data loss</b> will occur if the respective precautionary measures are not taken.
$\triangle$	Warning	This symbol in connection with the signal word indicates that <b>personal injury</b> may occur if the respective precautionary measures are not carried out.
$\triangle$	Read	This symbol, which is attached to the device, indicates that the device-specific documentation must be followed. This is necessary in order to recognize the nature of the potential danger and take the necessary measures to prevent it.  Manipulations not described in the operating manual or expressly forbidden will jeopardize your warranty rights.
⇒	Reference	This symbol refers to further information in other manuals, chapters, or sections.
abc <sup>1</sup>	Footnote	Remarks at the end of a page that <b>refer to</b> specific text passages and are marked with a number placed in superscript.
*	Action in- struction	The steps (marked with an asterisk) must be carried out one after another in the reading order.

or PELV-circuits)

# 2 Identifying the device version

The nameplate is glued laterally to the device.





### Caution

The voltage supply that is connected must correspond to the voltage specified on the nameplate!

(1)	Basic type
707071	dTRANS T06
(2)	Version
8	Standard with default settings
9	Customer-specific configuration (specifications in plain text)
(3)	Voltage supply
23	AC 110 to 240 V +10/-15 %, 48 to 63 Hz
29	DC 24 V +10/-15 % (The device has only to be connected at SELV- or PELV-circuits)
(4)	Extra codes <sup>a</sup>
000	None
018	RS485 interface Modbus RTU and relay output
058	SIL and PL approval (yellow front foil)
062	DNV GL approval

	(1)	/	(2)	-	(3)	/	(4)		
Order code		/		-		/		,	а
Order example	707071	/	8	-	23	/	000	,	000

<sup>&</sup>lt;sup>a</sup> List extra codes in sequence, separated by commas

# 2.1 Scope of delivery

- Type 707071 in the ordered version
- Operating manual
- ⇒ The interface description is available as a download.

### 2.2 Accessories

Item	Part no.
Setup program on CD-ROM, multilingual	00668006
USB cable A-connector to Micro-B connector, length 3 m, for type 707071	00616250
Screw-on end clamp for mounting rail	00528648

### 2.3 Device software version, fabrication number

⇒ Chapter 8.1 "Version"

### 2.4 Service addresses

⇒ See back cover



### Read

This operating manual is the translation of the **German manual**. It is valid for the following hardware and software version(s):

Channel: 348.01.01, 348.02.01 Diagnostics: 349.02.01, 349.02.01



### Important information

Keep the operating manual in a place that is accessible to all users at all times. Use the device software version to check that the documentation matches your device.



### Caution

All the necessary settings are described in the operating manual.

Manipulations that are not described in the operating manual or that are expressly forbidden will jeopardize your warranty rights and may render the assured function inoperative!

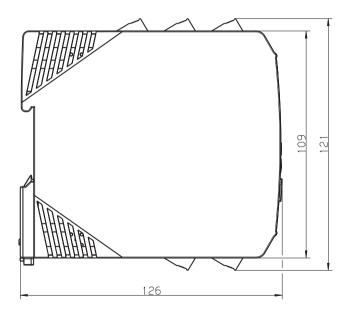
Any interference with the inside of the device is prohibited!

Repairs may be only performed by JUMO in the company's headquarters in Fulda. If you have any problems, please contact the nearest branch office or the head office.

# 3 Mounting

# 3.1 Dimensions





# 3.2 Mounting site, DIN-rail mounting

### Warning



The device is **not** suitable for installation in potentially explosive areas. The device is clipped to a 35 mm DIN-rail (DIN EN 60715) from the front and locked into place by pressing downwards.

- The ambient conditions at the installation site must meet the requirements specified in the technical data.
  - ⇔ Chapter 9 "Technical data"



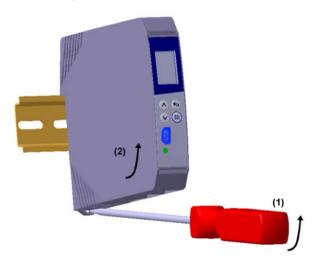
- Ensure vibration-free installation to prevent the screw connections from working loose!
- The atmosphere must be free from aggressive media (e.g. acids and lyes), as well as free from dust, flour, or other suspended solids to prevent blocking of the cooling slots!

### 3.3 Close mounting

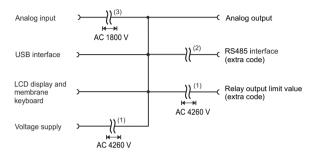
- Maintain the minimum distance of 20 mm to the top and the bottom.
  - 1. So that the release slot can still be accessed with a screwdriver from the bottom.
  - 2. So that when dismounting, the device can be swiveled upwards and removed from the DIN rail.
- Several devices can be mounted right next to one another without a minimum distance.

# 3.4 Dismounting

- Place screwdriver in release catch and press upwards (1).
- Remove housing upwards (2).



### 3.5 Galvanic isolation



- (1) The voltage specifications correspond to the alternating test voltages (effective values) according to EN 61010-1:2011-07 for type testing.
- (2) Functional galvanic isolation for the connection of SELV or PELV circuits.
- (3) The voltage specification corresponds to the alternating test voltage (effective value) according to DIN EN 61010-1:2011-07 for type testing to connect SELV or PELV electrical circuits [secondary electrical circuits which are derived from supply current circuits with overvoltage category III (>150 V ≤ 300 V)].

### 3.6 Use of the USB interface

- The USB interface is only designed for service use over a limited period, since the device switches the output signal to safe state when in SIL operation during data transmission with the setup program!
- The RS485 interface is suitable for unlimited operation of the interface in a fixed installation.

### 4 Electrical connection

### 4.1 Installation notes

- Check to see if the device is installed in a manner appropriate to the application (temperature measurement) and that it is operated within the admissible plant parameters.
- The device is intended to be installed in switch cabinets, machines, or plants.
   Ensure that the customer's fuse protection does not exceed 20 A.
- Disconnect the device from the mains voltage on all poles prior to starting service or repair work.
- All incoming and outgoing lines without a connection to the power supply network must be laid with shielded and twisted lines. Connect the screen on the device to ground.
- Do not lay the input and output cables close to components or lines through which current is flowing.
- Do not connect any additional loads to the screw terminals for the voltage supply of the device.
- Both the choice of cable material for the installation as well as the electrical connection of the device must conform
  to the local requirements of VDE 0100 "Regulations on the Installation of Power Circuits with Nominal Voltages
  below 1000 V" or the appropriate regulations for the country.
- Suitable measures must be taken to protect the relay circuit.
   The maximum switching capacity is 240 V, 3 A (resistive load).
  - The electromagnetic compatibility conforms to the standards and regulations cited in the technical data.

    ⇒ Chapter 9 "Technische Daten"
- As part of the startup, it is recommended to carry out a test run of the system until the measuring range is exceeded (output of a diagnostic error) so that the output signal switches to safe state.
- Under operating conditions the temperature on the screw terminals can exceed 60° C.
   This can destroy the cable isolation of the connection wires.
   The cabling must be temperature resistant up to 80 °C.

### Caution



The electrical connection and settings in the configuration level up to system startup may only be carried out by qualified personnel.

### 4.2 Connection diagram

The connection is made via slot-encoded screw terminals.

**Note:** Please ensure that any terminals removed for wiring or device exchange are reconnected at the correct position.



Conductor	Admissible cross section					
Rigid or flexible	0.2 to 2.5 mm <sup>2</sup>					
Flexible with ferrule with or without plastic sleeve	0.25 to 2.5 mm <sup>2</sup>					
AWG	12 to 24					
2 rigid / flexible conductors with equal cross section	0.2 to 1 mm <sup>2</sup>					
2 flexible conductors with equal cross section, ferrule without plastic sleeve	0.25 to 1 mm <sup>2</sup>					
2 flexible conductors with equal cross section, ferrule with plastic sleeve	0.5 to 1.5 mm <sup>2</sup>					
AWG according to UL/CUL	12 to 30					
Tightening torque of screws: max. 0.6 Nm						



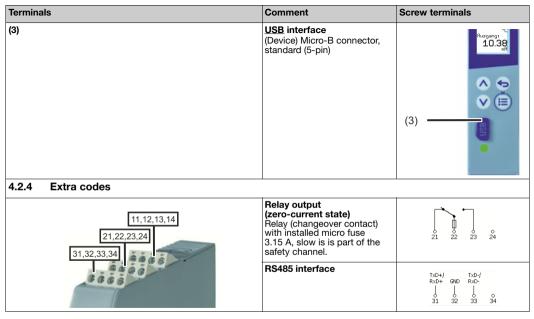
### Caution

See special notes relating to the heat resistance of cables.

Terminals		Comment	Screw terminals
4.2.1	Analog input (part of the safe	ty channel)	
	A 6	RTD temperature probe in two-wire circuit	51 52 53 54 9 ft
	<b>∨</b> (iii)	RTD temperature probe in three-wire circuit	51 52 53 54
		RTD temperature probe in four-wire circuit	51 52 53 54 J # #
	[51,52,53,54] [41,42,43,44]	Resistance/potentiometer in two-wire circuit	51 52 53 54
		Resistance/potentiometer in three-wire circuit	51 52 53 54
■ Defa	ult setting	Resistance/potentiometer in four-wire circuit	51 52 53 54

Terminals	Comment	Screw terminals
392.1 hasping 13 3.92	Potentiometer/WFG A: Start resistance S: Loop resistance E: End resistance	51 52 53 54 OA O OS OE
<b>⋄</b> • • • • • • • • • • • • • • • • • • •	Thermocouple	51 52 53 54
	Double thermocouple (galvanically isolated) The thermocouple on terminals 53 and 54 is only used for sensor breakage detection and is not dis- played as a measured value.	51 52 53 54
51,52,53,54	mV input (0 to 1 V)	51 52 53 54   0   0 - 0   0 - 0   0
41,42,43,44	4 to 20 mA	51 52 53 54 9 9 0 0
[±=,0±,2±,1±	0 to 20 mA	51 52 53 54
	0 to 10 V	51 52 53 54 0 0 0 1 0 0 - + +

Terminals Comment Screw terminals		
		Screw terminals
4.2.2 Analog output (part of the safety ch	annel)	
<b>Note:</b> If an open current output is detected, this leads $\mathbf{Remedy}$ : Install a 470 $\Omega$ resistor until the output in the		
	0(4) to 20 mA	41 42 43 44
51,52,53,54 41,42,43,44	0(2) to 10 V	41 42 43 44 0 0 0 0 + U <sub>X</sub> -
4.2.3 Voltage supply (on the nameplate)		
⇒ Chapter 2 "Identifying the device version"		
11,12,13,14 21,22,23,24 31,32,33,34	AC: L1 line conductor N Neutral conductor  DC: (L+) (L-) The device has only to be connected at SELV- or PELV-circuits	LI N (L+) (L-)                  11   12   13   14



Default setting

# 5 Startup of the device

### 5.1 Display and control elements

\* When the voltage supply is set up, a self-test begins during which the back-lit display shows white pixels for 2 s and then black pixels for 2 s. The LED lights up simultaneously red and green.

The self-test



is followed by a language request Device data



and then the main measured value appears:



⇒ If an error message appears, see Chapter 11 "Error messages".

### 5.2 Setting the display after device is switched on

The main measured value appears on the screen in German (default setting).

Once a probe has been connected, the device displays a measured value of 24.0 °C and an output signal of 10.38 mA as an example here.



### Important information

If something else is to be displayed after switch-on, this can be adjusted as follows:

⇒ Chapter 7.3.1 "Normal display"

Since the relay output is set to "no function" at the factory, the relay does not respond at all.

⇒ Chapter 7.6 "Limit value monitoring"

As long as the measured value is detected correctly, it switches, depending on the set limit value and switching behavior. In the event of an error, the relay is switched off (inactive "0").

Legend	Comment	(1) Diagram  (1) Output: 7.33	
1	LCD display Black/white with backlight, 64 x96 pixels  Configuration level locked SIL Operation SIL -0 K1 Relay active "1"  Measur.: 32.9  Output: 7.33		
2	Keys  Increase value / previous menu item  Reduce value / next menu item  Back / cancel change	(2)	
4	Doe level lower in the menu, confirm change  LED Lights up • green if the diagnostic function does not detect any errors. Lights up • simultaneously red and green upon device restart, during simulation of analog output, and during active setup data transfer. Lights up • red if the diagnostic function detects errors (e.g. if the limits for the signal type are exceeded in the signal flow figure below).		

### 5.3 Extra code SIL

For a device with extra code 058, SIL operation is activated per default and shown in the display at the top left.

### The following specifications apply in SIL operation:

- 1.) Only the following sensor types can be set at the analog input: Double thermocouple, RTD temperature probe or 4 to 20 mA
- 2.) Only the signal type 4 to 20 mA can be set at the analog output, simulation cannot be activated and only high or low can be selected as an error signal, not any value.
- 3.) The following changes during operation:

  Double confirmation for safety relevant parameters is active.
- 4.) Diagnostics:

No check of analog output, safe state during setup transmission, temperature range of terminal is monitored, device enters safe state when leaving the range.

5.) Display:

Display of SIL in top left corner

6.) The membrane keyboard on a device with extra code 058 is yellow:





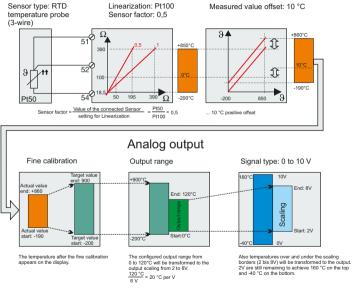
### Important information

It is possible to deactivate SIL in the setup program:

### 5.4 Signal flow

The following example shows which parameters influence the measured value from the analog input to the analog output.





Here is a summary of the parameters from the figure above:

# Analog input:

 Sensortype:
 RTD temperature probe (2-wire)

 Linearization:
 Pt100, IEC 60751:2008, ITS-90

 Noise suppression:
 Yes

 Sensor factor.
 1.00

 Line resistance:
 0.5 Ohm

 Filter time constant
 0.1 s

 Measured value offset:
 10.00 °C

Fine calibration

Fine calibration startvalue (actual): -190.00 °C
Fine calibration end value (actual): 860.00 °C
Fine calibration startvalue (target): -200.00 °C
Fine calibration end value (target): 900.00 °C

# Analog output:

 Signal type:
 0 ... 10 V

 Output range start:
 0.00 °C

 Output range end:
 120.00 °C

 Scaling start:
 2.00 V

 Scaling end:
 8.00 V

 Simulation:
 off

Reversion of the output: No reversion
Error signal: Negative signaling

Replacement value: -0.20 V
Response to GW error: active
Signal from diagnosis error: All errors

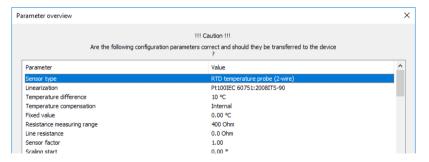
# 6 Safety Manual



### Warning

All safety relevant parameters must be validated by the plant operator. In devices with extra code 058 the SIL operation is activated per default.

The settings for SIL operation are described in Chapter 5.3 and the default settings in Chapter 7 are marked (**bold**) and SIL-Parameter are marked yellow. Via Setup-program the data can be read from the device and after verification of the Parameter overview transferred back into the device.



## 6.1 Brief description, intended use

⇒ Chapter 1 "Brief description".

### 6.2 Validity of the safety manual



### Note

The evaluation described in this safety manual in terms of functional safety and display of certificates is valid for the specified transmitter in SIL operation, including probe versions.

⇒ Safety manual (probe for connection to 707071 Variant 1 and 2)

### 6.3 Special operating statuses

### 6.3.1 Behavior after a power failure

Analog output issues ≤ 3.6 mA; relay output (extra code 018) limit value is deactivated.

After the return of the mains voltage, the device starts as described in Chapter 5 and converts the measured value at the analog input in the configured output signal.

### 6.3.2 During setup data transfer

If LED illuminates • simultaneously red and green, the device is transferred to a safe state until the setup data reaches the device and a data comparison is carried out.



# 6.3.3 After alteration of the configuration level (at the device or through setup)

The device carries out a plausibility check that can also trigger an error message.

- ⇔ Chapter 12 "What to do, if ..." "Check dependent parameters"
- ⇔ Chapter 11 "Error messages"

### 6.3.4 Issue of an error signal (safe state)

In SIL operation, the measured value at the analog input is always issued at the analog output 4 to 20 mA.

The limit values according to Namur NE 43 ( $\leq$  3.6 or  $\geq$  21 mA) are only issued when internal errors and probe errors are identified. However, the behavior of the analog output in case of limit value errors is configurable.

⇔ Chapter 7.5.8 "Response for limit error"

### 6.4 Relevant standards

Type 707071 SIL fulfills the requirements for SIL 2, or SIL 3 in redundant use, according to DIN EN 61508 and PL c/PL d according to DIN EN ISO 13849-1, as well as the requirements of DIN EN 60730-2-9.

The systematic suitability is defined at SC = 3 for HW and SW.

This means that SIL 2 or PL c for HFT = 0 (individual device) and SIL 3 or PL d for HFT = 1 (2 devices) are achieved.

For the safety function up to SIL 3 according to DIN EN 61508 Part 1 to 7:

Functional safety of electrical/electronic/programmable electronic safety-related systems

DIN EN 60730-2-9:

Automatic electrical controls for household and similar use – Part 2-9: Particular requirements for temperature sensing controls

DIN EN ISO 13849-1:

Safety of machinery - Safety-related parts of control systems

DIN EN ISO 13849-2:

Safety of machinery - Safety-related parts of control systems - Part 2: Validation (ISO 13849-2)

# 6.5 Connection possibilities of the sensors

Variant	connected Sensors
Variant 1	RTD temperature probe in a 2-, 3- or 4-wire circuit
Variant 2	double thermocouple
Variant 3	4 to 20 mA

# 6.5.1 Terms and abbreviations according to DIN EN 61508 and DIN EN 61511.

Name	Description
Actuator	Part of a safety-related system that intervenes in the process to achieve a safe state.
EUC	EUC (equipment under control) Equipment, machine, apparatus, or system used for manufacturing, shaping materials, for transport, medical purposes, or other activities.
E/E/PE	Electrical/electronic/programmable electronic (E/E/PE): based on electrical (E) and/or electronic (E) and/or programmable electronic (PE) technology
Failure	End of the ability of a functional unit to perform a required function.
Diagnostic coverage	Partial reduction in the probability of critical hardware failures due to the use of automatic diagnostic tests.
Error	An abnormal condition that can cause a reduction or the loss of the ability of a functional unit to perform a required function.
Functional safety	A part of overall safety related to the EUC and EUC control system that depends on the proper function of the E/E/EP safety-relevant system, safety-relevant systems of other technology, and external equipment for risk reduction.
Functional unit	Unit consisting of hardware or software or both that is suitable for performing a specified task.
Dangerous failure	Failure of an element and/or subsystem, and/or system involved in implementing the safety function, which
	<ul> <li>a) prevents the safety function being executed on demand (on-demand operation type), or causes the failure of a safety function (operation with continuous demand), so that the EUC transitions to a dangerous or potentially dangerous state; or</li> </ul>
	b) reduces the probability of executing the safety function correctly on demand.

Name	Description
Safe failure	Failure of an element and/or subsystem, and/or system involved in implementing the safety function, which
	a) causes false triggering of the safety function, switching the EUC (or parts of it) to a safe state, or maintaining a safe state; or
	a) increases the probability of false triggering of the safety function, switching the EUC (or parts of it) to a safe state, or maintaining a safe state.
Hazard	Potential source of damage
Safety	Freedom from unreasonable risk
Safety function	A function that is performed by an E/E/PE safety-related system, safety-related system based on other technology, or external equipment for reducing risk with the goal of achieving or maintaining a safe state for the EUC taking into consideration a specified dangerous event
Safety integrity	The probability of a safety-related system performing the required safety function under all specified conditions within a specified period of time according to requirements.
Safety integrity level (SIL)	One of four discrete levels for specifying the requirement for safety integrity of the safety functions assigned to the E/E/PE safety-related system. Safety integrity level 4 represents the highest level of safety integrity, while safety integrity level 1 represents the lowest.
Safety-related system	System that both - performs the required safety functions that are necessary to achieve or maintain a safe state for the EUC, and - is intended to achieve the necessary safety integrity for the required safety functions on its own or with other E/E/PE safety-related systems, safety-related systems of other technology, or external equipment for risk reduction.
Safety instrumented system (SIS)	Safety instrumented system to perform one or more safety-related functions. A SIS consists of sensor(s), logic system, and actuator(s).
Lambda: λ	Failure rate per hour
Lambda <b>D</b> angerous: λ <sub>D</sub>	Rate of dangerous failures per hour
Lambda <b>D</b> angerous <b>D</b> etect: $\lambda_{DD}$	Rate of detected dangerous failures per hour

Name	Description
Lambda <b>D</b> angerous <b>U</b> ndetect:	Rate of undetected dangerous failures per hour
$\lambda_{DU}$	
Lambda Safe: λ <sub>S</sub>	Rate of safe failures per hour
Lambda Safe <b>D</b> etect: $\lambda_{SD}$	Rate of detected safe failures per hour
Lambda Safe <b>U</b> ndetect: $\lambda_{SU}$	Rate of undetected safe failures per hour
BPCS	Basic process control system
DC	Diagnostic coverage
FIT	Failure in time (1x10 <sup>-9</sup> per h)
HFT	Hardware failure tolerance
PFD	Probability of failure on demand
PFD <sub>avg</sub>	Probability of failure on demand average
PFH	Probability of dangerous failure per hour
MooN	Architecture with M from N channels
MTBF	Mean time between failures
MTTR	Mean time to restoration (mean time between discovery of the fault and repair of the system)
MRT	Mean repair time (mean time to repair the system)
SFF	Safe failure fraction
SIL	Safety integrity level
SC	Systematic capability
PTC	Proof test coverage (diagnostic coverage during repeat test)
Ti	Proof <b>T</b> est intervall

#### 6.5.2 Safety-relevant parameters

All following informations relate to the connection-Variant 3.

The following parameters were calculated using the formular in Chapter 6.5.5 for  $T_i = 1, 3$ , and 5 years.

### 6.5.3 Failure rates and SFF for 707071/X - 23/XXX (AC240V)

Variant 3 4 to 20 mA (without sensor technology 10o1D architecture)	λ <sub>S</sub> [FIT]	λ <sub>DD</sub> [FIT]	λ <sub>DU</sub> [FIT]	SFF		PFD avg (Proof test A PTC=75 %)	PFD avg (Proof test B PTC=70.9 %)	PFD avg (Proof test C PTC=45.4 %)
T <sub>i</sub> = 1 year	49.5	2049.8	151.1	93 %	1.51 × 10 <sup>-7</sup>	$2.31 \times 10^{-3}$	2.55 × 10 <sup>-3</sup>	$4.07 \times 10^{-3}$
T <sub>i</sub> = 3 years						$3.30 \times 10^{-3}$	3.49 × 10 <sup>-3</sup>	4.67 × 10 <sup>-3</sup>
T <sub>i</sub> = 5 years						$4.29 \times 10^{-3}$	$4.43 \times 10^{-3}$	$5.27 \times 10^{-3}$

see examples in Chapter 6.5.5

## 6.5.4 Failure rates and SSF for 707071/X – 29/XXX (DC24V)

Variant 3 4 to 20 mA (without sensor technology 10o1D architecture)	λ <sub>S</sub> [FIT]	λ <sub>DD</sub> [FIT]	λ <sub>DU</sub> [FIT]	SFF	PFH (1/h)	PFD avg (Proof test A PTC=69.9 %)		PFD avg (Proof test C PTC=44.0 %)
T <sub>i</sub> =1 year	49.5	2088.8	158.1	93 %	$1.58 \times e^{-7}$	2.73 × 10 <sup>-3</sup>	2.86 × 10 <sup>-3</sup>	$4.34 \times 10^{-3}$
T <sub>i</sub> = 3 years						3.70 × 10 <sup>-3</sup>	$3.80 \times 10^{-3}$	4.95 × 10 <sup>-3</sup>
T <sub>i</sub> = 5 years						4.67 × 10 <sup>-3</sup>	$4.74 \times 10^{-3}$	5.56 × 10 <sup>-3</sup>

#### 6.5.5 Calculation of PFD ava

The operator defines the following topics:

- Proof test interval T<sub>i</sub>
- Planned operating duration mission time T<sub>M</sub> and
- the PTC-value for the performed Proof test (A,B or C)

The mission time  $T_M$  has to be at least equal the time for the proof test interval  $T_i$ , but not exceed the Lifetime of 10 years. This must be taken into consideration when evaluating the probability of a dangerous failure  $PFD_{avg}$  of the sensor system. In the case of a single-channel system architecture, the mean probability of a dangerous failure  $PFD_{avg}$  of the transmitter can be calculated from the following formula:

#### Formula:

PFD <sub>avg</sub>	$= \lambda_{dd} \cdot MTTR + PTC \cdot \lambda_{du} \cdot \left(\frac{T_i}{2} + MRT\right) + \left(1 - PTC\right) \cdot \lambda_{du} \cdot \frac{T_M}{2}$
$\lambda_{dd}$	Rate of detected dangerous failures per hour
$\lambda_{du}$	Rate of undetected dangerous failures per hour
MTTR	Mean Time To Restoration, (mean time between discovery of the fault and repair of the system)
PTC	Proof Test Coverage (diagnostic coverage during repeat test)
Tı	Proof <b>T</b> est <b>i</b> nterval (Interval that can be defined by the the plant operator)
MRT	Mean Repair Time (mean time to repair the system)
T <sub>M</sub>	Mission Time, Planned operating duration (10 years = 87600 hours)

Type 707071, 240V, without sensor, examples:

Proof test	λ <sub>dd</sub> [Fit]		MTTR [h]	PTC [%]	T <sub>i</sub> [h]	MRT [h]	Т <sub>м</sub> [h]	PFD <sub>avg</sub>
Α	2049,8	151,1	72	75	8760	72	87600	2,31 ·10 <sup>-3</sup>
	$PFD_{avg} = 2049.8 \cdot 10^{-9}  \frac{1}{h} \cdot 72  h + 0.750 \cdot 151.1 \cdot 10^{-9}  \frac{1}{h} \left( \frac{8760  h}{2} + 72  h \right) + \left( 1 - 0.750 \right) \cdot 151.1 \cdot 10^{-9}  \frac{1}{h} \cdot \frac{87600  h}{2} = 2.31 \cdot 10^{-3}$							
В	2049,8	151,1	72	70,9	8760	72	87600	2,55 ·10 <sup>-3</sup>
	$PFD_{avg} = 2049.8 \cdot 10^{-9} \cdot \frac{1}{h} \cdot 72 \cdot h + 0,709 \cdot 151,1 \cdot 10^{-9} \cdot \frac{1}{h} \cdot \left( \frac{8760 \cdot h}{2} + 72 \cdot h \right) + \left( 1 - 0,709 \right) \cdot 151,1 \cdot 10^{-9} \cdot \frac{1}{h} \cdot \frac{87600 \cdot h}{2} = 2,55 \cdot 10^{-3}$							
С	2049,8	151,1	72	45,4	8760	72	87600	4,07 ·10 <sup>-3</sup>
	$PFD_{avg} = 2049.8 \cdot 10^{-9}  \frac{1}{h} \cdot 72   h  +  0.454 \cdot 151.1 \cdot 10^{-9}  \frac{1}{h} \cdot \left( \frac{8760   h}{2} + 72   h \right) \\ + \left( 1 - 0.454 \right) \cdot 151.1 \cdot 10^{-9}  \frac{1}{h} \cdot \frac{87600  h}{2} \\ = 4.07 \cdot 10^{-3}   \frac{1}{h} \cdot \frac{10^{-9}   h}{2} + \frac{1}{h} \cdot \frac{10^{-9}   h}{2} +$							

Information:  $1 \text{ Fit} = 1 \cdot 10^{-9} \frac{1}{h}$ 

### 6.6 Determining the safety integrity level (SIL)

The achievable safety integrity level is determined by the following safety-related parameters:

- Average probability of dangerous failures of a safety function on demand (PFD<sub>avg</sub>),
- Hardware fault tolerance (HFT) and
- Safe failure fraction (SFF).

The specific safety-related parameters for the 707071 measuring system can be found in the table in the "Safety-related parameters" chapter. They apply to the instrument with extra code 018 and 058.

The following table shows how the "safety integrity level" (SIL) depends on the "average probability of dangerous failures of a safety function of the entire safety-related system" (PFD<sub>avg</sub>) according to DIN EN 61508. The "low demand mode" is considered here, i.e. the demand rate for the safety-related system averages once a year.

Table for high demand PFH and low demand PFD

Safety integrity level (SIL)	Operating mode with high demand rate <b>PFH</b> (high demand mode)	Operating mode with low demand rate PFD <sub>avg</sub> (low demand mode)
4	$\geq 10^{-9} \text{ to } < 10^{-8}$	$\geq 10^{-5} \text{ to } < 10^{-4}$
3	$\geq 10^{-8} \text{ to } < 10^{-7}$	$\geq 10^{-4} \text{ to } < 10^{-3}$
2	$\geq 10^{-7} \text{ to } < 10^{-6}$	$\geq 10^{-3} \text{ to } < 10^{-2}$
1	$\geq 10^{-6} \text{ to } < 10^{-5}$	$\geq 10^{-2} \text{ to } < 10^{-1}$

#### 6.6.1 Safety integrity of the hardware

According to DIN EN 61508, a distinction must be made between systems of type A and systems of type B.

A subsystem can be considered to be type A if, for the components required to achieve the safety function,

- the failure behavior of all components used is sufficiently defined, and
- the behavior of the subsystem can be fully determined under error conditions; and
- reliable failure data from experience in the field exists for the subsystem to show that the assumed failure rates for detected and undetected dangerous failures are achieved.

A subsystem can be considered to be type B if, for the components required to achieve the safety function,

- the failure behavior of at least one of the components used is not sufficiently defined, or
- the behavior of the subsystem cannot be fully determined under error conditions, or
- no sufficiently reliable failure data from experience in the field exists for the subsystem to support the utilized failure rates for detected and undetected dangerous failures.

The type 707071 transmitter corresponds to a type B system.

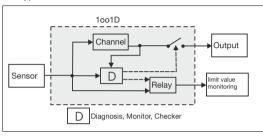
The following table shows the achievable safety integrity level (SIL) depending on the safe failure fraction (SFF) and the hardware fault tolerance (HFT) for safety-related type B subsystems.

For 707071 the following table applies:

Safe failure fraction (SFF)	Hardware fault tolerance (HFT) for type B				
	0	1	2		
<60 %	Not allowed	SIL 1	SIL 2		
60 to <90 %	SIL 1	SIL 2	SIL 3		
90 to <99 %	SIL 2	SIL 3	SIL 4		
≥ 99 %	SIL 3	SIL 4	SIL 4		

### 6.6.2 Safety-relevant system properties

The type 707071 transmitter is realized as a 1001D architecture.



#### The following are monitored:

- Probe break
- Probe short circuit
- Random hardware failure in the sensor channel

Safety feature	Requirement / comment
SIL	SIL2
Systematic suitability of HW and SW	SC3
Operating mode in terms of safety function	Operating mode with low and high demand rate possible on a customer-specific basis
Safety-critical inputs	Temperature sensor input for double thermocouple and RTD temperature probe with 2, 3, and 4-wire technology 4-20 mA current input
Safety-relevant inputs	Setup and parameterization
Safety-critical output	Analog output 4 to 20 mA Relay output (extra code 018)
Subsystem type	Туре В

Safety feature	Requirement / comment
707071 safety architecture	10o1D This corresponds to architecture category 2 according to DIN EN ISO 13849, i.e. the system has a safety channel and an additional diagnostics channel.
Hardware failure tolerance	HFT = 0
Safe failure fraction	SFF ≥ 90 %
CCF	If the system is used redundantly: calculation according to DIN EN 61508 Part 7 Appendix D and/or DIN EN ISO 13849-1 Table F.1 at least 65
Average failure probability of a safety function on demand (overall system)	SIL 2: Low demand: PFD <sub>avg</sub> < 10 <sup>-2</sup> High demand: PFH < 10 <sup>-6</sup>
Interval for the proof test T <sub>i</sub>	max. 10 years
Lifetime	10 years
Planned operating duration Mission time (T <sub>M</sub> )	max. 10 years
Architecture according to DIN EN ISO 13849-1	Category 2
MTTF <sub>d</sub> -DC <sub>avg</sub> according to DIN EN ISO 13849-1 Table K.1	PL c: ≥ 22 years (DC <sub>avg</sub> ≥ 60 %)
Modes of operation and software class according to DIN EN 60730-2-9	The system has the following modes of operation: 2K Only in the case of redundancy: 2N Software class C

### 6.6.3 Redundant use of the system

If the transmitter is used redundantly (HFT > 0), it can meet SIL 3 according to DIN EN 61508-2, 7.4.3.2 (systematic suitability) and 7.4.4.2.4 (suitability of the architecture).

SIL of the used Sensor		with 1001 sensor system and tempe-	max. achievable SIL of the system in redundant use (HFT = 1) of Sensor and temperature transmitter
1	1	1	1
1	2	1	2
2	2	2	2
2	3	2	3
3	3	2	3

#### 6.6.4 Sensor connection possibilities

The connection of RTD temperature probes with 2, 3, and 4-wire technology or double thermocouples is described in the safe-ty manual (probe for connection to 707071 Variant 1 and 2).

### 6.7 Determining the achieved performance level PL

The following safety-related parameters are required to determine the performance level of components/devices:

As further parameters to be observed, operational aspects such as the demand rate and/or the test rate of the safety function can also influence the resulting PL.

Excerpt from DIN EN ISO 13849-1



#### Note

This excerpt contains references to the complete standard DIN EN ISO 13849-1, which are therefore not reproduced in this chapter

## 6.7.1 Terms and abbreviations according to standards series DIN EN ISO 13849

Formula symbol or abbreviation	Description	Definition or location
PL (a, b, c, d, e)	Designation for the performance level	Table 3 in DIN EN ISO13849-1
AOPD	Active opto-electronic protective device (e.g. light barrier)	Annex H
B, 1, 2, 3, 4	Designation for the categories	Table 7
B <sub>10d</sub>	Number of cycles in which a dangerous failure occurred in 10 % of a random sample of the observed pneumatic or electromechanical components that are subject to wear (mean time to dangerous failure)	Annex C
Cat.	Category	3.1.2
CC	Current converter	Annex I
CCF	Common cause failure	3.1.6
DC	Diagnostic coverage	3.1.26
DC <sub>avg</sub>	Average diagnostic coverage	E.2
MTTF	Mean time to failure	Annex C
MTTF <sub>c</sub>	Mean time to critical failure	3.1.25
MTTF <sub>d</sub>	Mean time to dangerous failure	
n, N, N	Number of units	6.3, D.1
N <sub>low</sub>	Number of SRP/CS with PL <sub>low</sub> in an SRP/CS combination	6.3
PL	Performance level	3.1.23
PLC	Programmable logic controller	Annex I
PL <sub>low</sub>	Lowest performance level of an SRP/CS in an SRP/CS combination	6.3

Formula symbol or abbreviation	Description	Definition or location
PLf	Required performance level	3.1.24
T <sub>M</sub>	Mission time (functional life, designated period of utilization)	3.1.28
T <sub>10d</sub> -value	Reference value for a preventative replacement (10 % of the B10d value). At this value, a dangerous failure has already occurred for approx. 63 % of all components. In this case, the standard DIN EN ISO 13849-1 recommends replacement.	

The following table shows the achievable PL level for the two voltage versions each with relay output (extra code 018):

### 6.7.2 Calculations of the DIN EN ISO 13849-1 performance level – 707071/X - 23/XXX (AC240V)

Variant	MTTF <sub>d</sub>	DC <sub>avg</sub>	CCF	PL
4 to 20 mA also with relay output (without sensor technology 10o1D architecture)	52 years	93.54 %	75 points	PL c

## 6.7.3 Calculations of the DIN EN ISO 13849-1 performance level – 707071/X - 29/XXX (DC24V)

Variant	MTTF <sub>d</sub>	DC <sub>avg</sub>	CCF	PL
4 to 20 mA also with relay output (without sensor technology 1oo1D architecture)	51 years	93.28 %	75 points	PL c

The two variants of the dTRANS T06 meet the architecture requirements for a category 2 system. The necessary limit values according to DIN EN ISO 13849-1, Table K.1 for **performance level c** and the fundamental and established safety principals are adhered to for all voltage versions of type 707071 considered.

If the temperature transmitter is used redundantly (i.e. HFT = 1), the requirements for a category 3 system are adhered to. The

necessary limit values according to DIN EN ISO 13849-1, Table K.1 for **performance level d** are met here for both voltage versions.

The following chart can be used to determine the PL if the  $MTTF_d$  value of the sensor is 100 years. The reached DC for identifying the errors of the sensor of the temperature transmitter will be calculated at (HFT = 1) with  $\geq$  60% in a redundant application.

PL of the used Sensor MTTF <sub>d</sub> =100 years		max. achievable PL of the system in redundant use (HFT = 1) DC $\geq 60\%$
b	b	d
С	С	d
d	С	d
е	С	d

#### 6.7.4 Risk reduction through the control system

In order to meet safety aims for the machine, the entire design process must be followed. The design of the SRP/CS (safety-related part of a control system) is a necessary part of the entire design process in order to provide the risk reduction required. This can only be achieved with a PL that achieves the required risk reduction. By installing a protective guard or protective device, the design of the SRP/CS is part of the risk reduction strategy.

The features of each safety function (see section 5) and the required performance level must be described and documented in the specification of the safety requirements.

In this part of DIN EN ISO 13849-1, the performance levels are defined in the form of the probability of a dangerous failure per hour. Five performance levels (a to e) have been specified (see Table).

Performance level (PL)	Average probability of a dangerous failure per hour 1/h
а	$\geq 10^{-5} \text{ to} < 10^{-4}$
b	$\geq 3 \times 10^{-6} \text{ to} < 10^{-5}$

	Average probability of a dangerous failure per hour 1/h
С	$\geq 10^{-6} \text{ to} < 3 \times 10^{-6}$
d	$\geq 10^{-7} \text{ to} < 10^{-6}$
е	$\geq 10^{-8} \text{ to} < 10^{-7}$

NOTE: in addition to the average probability of a dangerous failure per hour, further measures are required to achieve the PL.

### 6.8 Other applicable device documentation

For the transmitter type 707071, the measures, values, and requirements specified in this operating manual regarding installation, electrical connection, function, and startup must be observed.

### 6.9 Behavior during operation and in case of malfunction

The behavior during operation is described in Chapter 5 "Startup of the device" and in case of malfunction is described in Chapter 11 "Error messages".

A functional test must be performed after startup, repair in the safety system, or a change in safety-related parameters. If an error is detected during a functional test, measures must be taken to once again ensure the functional capability of the safety system. This, for example, can be done by replacing the logic unit.

Appropriate documentation of the tests performed is recommended.

### 6.10 Regular tests

The device test can be carried out as follows:

- Proof test A: complete test by the manufacturer; the device must be sent to the manufacturer for this purpose.
- Proof test B: comprehensive test; the device must be removed from the operating facility for this purpose.
- Proof test C: simplified test; the device can remain in the operating facility for this purpose.

Depending on the voltage supply of the device, different values occur for the proof test coverage (PTC):

#### 6.10.1 Proof test A

(corresponds to factory calibration)

For a complete check, the device must be removed from the operating facility and sent to the manufacturer.

⇒ For service addresses see back cover

Voltage supply	Detection of dangerous undetected failures ( $\lambda_{DU}$ )	PTC
AC 110 to 240 V +10/-15 %, 48 to 63 Hz	0.750	75 %
DC 24 V +10/-15 %	0.699	69.9 %

### 6.10.2 Proof test B

Step	Action	Please note
1	Disconnect all test piece connections. Test the resistance between the following connections with an ohmmeter: 21 to 22: low-resistance, 0 $\Omega$ 21 to 23: high-resistance, ohmmeter overrun 22 to 23: high-resistance, ohmmeter overrun	Test piece is completely disconnected from the operating facility and without power supply. Verification that there is no short circuit in the area of connections 21 to 23 and 22 to 23.
2	Test the resistance between the following connections with an ohmmeter: 41 to 42: $>10\ k\Omega$	Verification that there is no short circuit in the area of the analog output connection terminal.
3	Test the resistance between the following connections with an ohmmeter: 52 to 51: $>$ 10 k $\Omega$ 53 to 51: $>$ 10 k $\Omega$ 54 to 51: $>$ 10 k $\Omega$ 53 to 52: $>$ 10 k $\Omega$ 54 to 52: $>$ 10 k $\Omega$ 54 to 53: $>$ 10 k $\Omega$ 54 to 53: $>$ 10 k $\Omega$	Verification that there is no short circuit in the area of the measurement input connection terminal.
4	Connect short-circuit jumper between connection 41(+) and connection 42(-), restore energy supply connection and switch on test piece, configure test piece for connection to RTD temperature probe sensor type in 4-wire connection and configure analog output for current signal (4 mA to 20 mA; error signal: negative signaling).  Connect current meter between connection 54(+) and 51(-) and measure the current: 200 µA to 300 µA can be expected.	determining the current are OK.

Step	Action	Please note
5	Connect resistance decade for simulation of the input signal that is appropriate for the chosen configuration. Verify whether the expected value (display value) corresponds to the input signal. Test the current device status of the test piece using the setup program. Status must be 'OK'. If, for example, Pt100 is configured, 0 °C must be displayed at the input at 100 $\Omega$ .	Verification that there is no error status internally if display correct without error signaling.
6	Produce line break for each of the 4 lines. The test piece must signal an error (display and LED).	Verification of proper function of the probe break/line break detection.
7	Switch off test piece and replace short-circuit jumper at the analog output with the current meter; connection 41(+) and connection 42(-). Switch on test piece again.  Check output signal by applying a corresponding reference signal using a resistance decade at two points; for the start of measurement (measuring range start up to +20 % of the range) and for the end of measurement (measuring range end up to -20 % of the range).  The analog output signal corresponding to the reference signal must be within the safety measurement deviation.  Furthermore, the display value must correspond to the reference signal according to the configuration.	chain for RTD is within the safe- ty measurement deviation.

Step	Action	Please note
8	Set limit value of the relay (function AF7) in the middle of the configured measuring range. Connect positive terminal of a voltage source (24 V $\pm 5$ %, 500 mA) to the terminal connection 22 via a resistor (240 $\Omega$ , 5 W). Connect the ground connection of the voltage source with the relay contact connections 21 and 23. Simulate an input signal close to the measuring range start using a resistance decade, and verify whether the specified signal and the transformed analog output signal correspond to the value expected (display value, current meter). Measure the voltage between the connections 22(+) and 21(-), as well as between 22(+) and 23(-) using the voltage meter. The measured voltage value between terminals 22 and 21 must be < 0.1 V, and must be 22.8 V to 25.2 V between terminals 22 and 23.	switched <b>below</b> the configured limit value.
9	Simulate an input signal close to the measuring range end using a resistance decade, and verify that the input signal corresponds to the value expected (display value). Measure the voltage between the connections 22(+) and 21(-), as well as between 22(+) and 23(-) using the voltage meter. The measured voltage value between terminals 22 and 21 must be 22.8 V to 25.2 V, and be < 0.1 V between terminals 22 and 23.	switched above the configured
10	Disconnect line to the measurement input connection 51. The test piece must signal an error (display and LED). The current meter must display a value $\leq 3.6$ mA as an analog output signal. Measure the voltage between the connections 22(+) and 21(-), as well as between 22(+) and 23(-) using the voltage meter. The measured voltage value between 22 and 21 must be $<$ 0.1 V, and must be 22.8 V to 25.2 V between 22 and 23. The relay therefore drops out.	function that the analog output signal corresponds to failure in- formation A, NE43, and the relay

54

Step	Action	Please note
11	Restore line to the measurement input connection 51. Both the display and the current meter at the analog output must display values that correspond to the input signal present close to the measuring range end. Relay must have picked up. The test piece must be in SIL operation and/or have a SIL configuration. Disconnect the line of the current meter at connection 42(+). The test piece must signal an error after approx. 5 s. Measure the voltage between the connections 22(+) and 21(-), as well as between 22(+) and 23(-) using the voltage meter. The measured voltage value between 22 and 21 must be < 0.1 V, and must be 22.8 V to 25.2 V between 22 and 23.	interruption of the output signal path (current signal), the internal test for a correct output signal identifies the interruption of the signal path and signals it. Relay drops out.
12	If active, deactivate SIL operation of the test piece. Configure test piece for connection to the thermocouple sensor type, NiCr-Ni, type 'k', internal cold junction, and configure analogue output to current signal (4 mA to 20 mA; error signal: negative signaling). Connect current meter between connection $54(+)$ and $51(-)$ and measure the current. No current must be measurable $(-0 \ \mu A)$ .	
13	Connect short-circuit jumper between connection 52(+) and connection 51(-). Check whether the temperature displayed by the display corresponds to the ambient temperature with a deviation of $\pm$ 5 °C.	Verification of proper function of the acquisition of the cold junc- tion temperature for thermocou- ples.
14	Configure test piece for connection to the double thermocouple sensor type, NiCrNi, type 'K', internal cold junction, and configure analogue output to current signal (4 mA to 20 mA; error signal: negative signaling). Test the resistance between the following connections with an ohmmeter: 53 to 51: display $<5\ \Omega$	Verification of proper function of the earthing switch for the sec- ond thermocouple

Step	Action	Please note
15	Switch off test piece and connect current meter using a burden of 500 $\Omega$ between connections 42(+) and 41(-). Switch on test piece and configure analog output for simulation of current output signal 21.2 mA. The output signal recorded using the current meter must be 21.18 mA to 21.22 mA. Configure analog output for simulation of current output signal 3.6 mA. The output signal recorded using the current meter must be 3.59 mA to 3.61 mA.	er stage of the analog output can drive the maximum permissible burden.

With proof test B, the following values for the proof test coverage (PTC) can be achieved:

Voltage supply	Detection of dangerous undetected failures ( $\lambda_{DU}$ )	PTC
AC 110 to 240 V +10/-15 %, 48 to 63 Hz	0.709	70.9 %
DC 24 V +10/-15 %	0.677	67.7 %

### 6.10.3 Proof test C

Step	Action		Please note	
1	Test the current device status of the test piece with the setup program. Status must be 'OK'			
2			Verification of the proper function of the analog output including whether the error signal values can be generated.	
	3.6 mA	3.59 to 3.61 mA		
	8 mA	7.99 to 8.01 mA		
	16 mA	15.99 to 16.01 mA		
	21.2 mA	21.19 to 21.21 mA		
3	Reactivate SIL operation. Disconnect the line of the analog ou The test piece must signal an error a Verify that the relay output (extra cod	after approx. 5 s.	Verification that in the event of interruption of the output current signal, the internal test identifies the interruption of the signal path and signals it. Relay drops out.	

With proof test C, the following values for the proof test coverage (PTC) can be achieved:

Voltage supply	Detection of dangerous undetected failures ( $\lambda_{DU}$ )	PTC
AC 110 to 240 V +10/-15 %, 48 to 63 Hz	0.454	45.4 %
DC 24 V +10/-15 %	0.440	44.0 %



#### Warning

After the mission time expires, the systems no longer meet the requirements according to their SIL certification.

#### 6.10.4 Recommended tests for temperature probes

To ensure safe and reliable operation of the thermometers, the following service and maintenance work must be performed: The following tests are recommended at certain intervals:

- Every 12 months, the insulation resistance of the measuring circuit must be measured against the protection fitting (for thermocouples: only for the insulated measuring circuit; in the case of multiple measuring circuits, the insulation test must also be performed between the individual measuring circuits). The minimal insulation resistance at room temperature should be 100 MΩ at 100 V.
- Damage and corrosion of thermometers protection tubes
- Corrosion and correct positioning of the contacts and terminals of cable connections
- Seals of terminal heads and cable bushings
- Interruptions due to "knocking" on the thermometer/measuring insert

Since the maximum operating temperature influences the drift behavior, the thermometer should be recalibrated or replaced at certain intervals to ensure reliable and precise temperature measurement.

The testing intervals are listed in the table below:

Maximum operating temperature	Pt – RTD temperature probe	Thermocouples
200 °C	5 years	5 years
550 °C	2 years	5 years
700 °C	1 year	2 years

1000 °C	Non-precious metal 1 year
	Precious metal 2 years
1500 °C	1 year

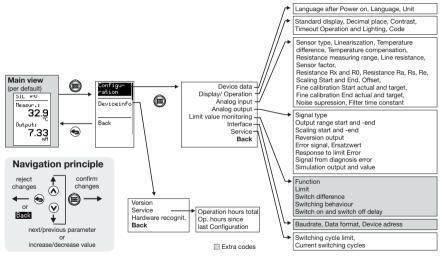


#### Note

The testing intervals for probes specified here are recommendations that must be adapted to the special conditions at the operating location and, if necessary, the user should perform the tests more regularly.

## 7 Configuration

#### 7.1 Overview



All the parameters are freely accessible, but they can be locked via a code on the device or with the setup program. Default settings are shown in **bold**. All parameters are listed in the following tables.

Parameters which are not required are automatically hidden depending on the setting.

## 7.2 Device data

Parameter		Comment	Value range (default setting in bold)	
7.2.1 Language	Language	German	German, English, French,	
		English	Spanish	
		French	†	
		Spanish	1	
7.2.2	Unit	A unit for the measured value can be set here.	°C, °F, %, text	
		°C	†	
		°F	†	
		%	1	
		Text:	1	
		Via the setup program, 9 characters can be entered here for another unit, e.g. Pa (Pascal)		
7.2.3	Language after	Here you can select whether a language query should appear	ON, OFF	
	power on	when the device is switched on.		

# 7.3 Display/operation

Param	eter	Comment	Value range (default setting in bold)
7.3.1 Normal display  This sets the view that appears after the voltage su is switched on.  ⇔ Chapter 7.1 "Overview"		⇒ Chapter 7.1 "Overview"	Main view, bar graph, limit value, drag indicator, TAG no. and info text,
		Main view	1/0 11110
		Bar graph	
		Limit value	
		Drag pointer	
		TAG no. and info text	
		I/O information  To display the connection diagram of sensor input, signal output, as well as the optional relay and interface assignment    SIL ==0	
7.3.2	Decimal place	No decimal place	None,
		One	one, two
		Two	
7.3.3	Contrast	Screen contrast: Difference in brightness between black and white pixels	0 to <b>5</b> to 10

Parameter		Comment	Value range (default setting in bold)
7.3.4	Lighting	Here, the background lighting of the display is set.	Always off, Always on,
		Always off: always switched off	When button is pressed
		Always on: always switched on	
		When button is pressed: The background lighting is only switched on when the keys are operated and it lights up until the time for the timeout backlight has expired.	
7.3.5	Time-out lighting	This setting is only available for button-activated light- ing. Here you can select how long the backlight should remain active after the last button operation.	0 to <b>30</b> to 100 sec
7.3.6	Time-out operation	Here, the waiting period is set for the return from the configuration level to the normal display.  ⇒ See "Operating overwiew" on page 2.	0 to <b>30</b> to 100 sec
		0 means: no automatic return to the normal display	
7.3.7	Code	To prevent unintentional changes to configuration data, a code for locking the configuration level can be set here.  0 means: code request switched off	<b>0</b> to 9999
		Important information	
		If the code is forgotten, a new code can be transferred to the device via the setup program.	
		⇒ Chapter 10.3 "Forgotten the code?"	

# 7.4 Analog input

Parameter	Comment	Value range (default setting in bold)
7.4.1 Sensor type	RTD temperature probe in 2-wire circuit	-
	RTD temperature probe in 3-wire circuit	-
	RTD temperature probe in 4-wire circuit	-
	Resistance/potentiometer in 2-wire circuit	-
	Resistance/potentiometer in 3-wire circuit	-
	Resistance/potentiometer in 4-wire circuit	-
	Resistance transmitter	-
	Thermocouple	-
	Double thermocouple	-
	mV input (0 to 1 V)	-
	4 to 20 mA	-
	0 to 20 mA	-
	0 to 10 V	-

SIL operation

7.4.2 Linearization	Comment	Measuring range
Linear	No sensor linearization	-
Pt100	IEC 60751:2008	-200 to +850 °C
Pt500, Pt1000	IEC 60751:2008	-200 to +850 °C
Pt50 GOST, Pt100 GOST	GOST 6651- 2009 A.2	-200 to +850 °C
Ni 100, Ni 500, Ni1000	DIN 43760:1987-09	-60 to +250 °C
Ni 100 GOST	GOST 6651-2009 A.5	-60 to +180 °C
Cu 50 GOST, Cu 100 GOST	GOST 6651-2009 A.3	-180 to +200 °C
Pt13Rh-Pt "R"	DIN EN 60584-1:2014	-50 to +1768 °C
Pt10Rh-Pt "S"		
Pt30Rh-Pt6Rh "B"		-50 to +1820 °C
Fe-CuNi "J"		-210 to +1200 °C
Cu-CuNi "T"		-200 to +400 °C
NiCr-Ni "E"		-200 to +1000 °C
NiCr-Ni "K"		-200 to +1300 °C
NiCrSi-NiSi "N"		-200 to +1300 °C
Fe-CuNi "L"	Thermocouple DIN 43710:1985-12	-200 to + 900 °C
Cu-CuNi "U"	Thermocouple DIN 43710:1985-12	-200 to +600 °C
Cromel COPEL® "L"	GOST R 8.585-2001	-200 to +800 °C
Cromel Alumel®		-270 to +1372 °C
W5Re-W20Re "A1"		-0 to +2500 °C
W5Re-W26Re "C"	ASTM E230M-11: 2011	-0 to +2315 °C

7.4.2 Linearization	Comment	Measuring range
W3Re-W25Re "D"	ASTM E1751M-09 (up to 2315 °C): 2009	-0 to +2315 °C
Platinel type PLII		-0 to +1395 °C
Customer-specific	This setting only appears if a customer-specific linearization has been entered via the setup program and transferred to the device.	

Parameter		Comment	Value range (default setting in bold)
7.4.3	Temperature difference		0 to <b>10</b> to 100
7.4.4	Temperature compens.	has been configured under linearization.	Internal, fixed value
7.4.5	Resistance measuring range	The measuring range can be selected here if "linear" or "customer-specific" has been set for linearization and "resistance/potentiometer" or "RTD temperature probe" has been set as the sensor type.	
7.4.6	Line resistance	Resistance of probe line (for 2-wire circuit)	<b>0.0</b> to 100 Ω
7.4.7	Sensor factor	Only for RTD temperature probe: For adjusting Pt25 to Pt1000 sensors to a different set linearization (e.g. Pt100). For example, a Pt100 linearization can be corrected with the sensor factor 0.5 in order to connect a Pt50 sensor.	0.25 to <b>1.00</b> to 10.00

Parameter	Comment	Value range (default setting in bold)
7.4.8 Resistance Rx  51 52 53 54 Rx  R <sub>0</sub> // R <sub>1</sub>	Parameter appears for setting "resistance/potentiometer" with 2, 3 or 4-wire circuit Here, the total ohmic resistance of the potentiometer area covered must be entered.	<b>0</b> to 400, 4,000 or 10,000 Ω
51 52 53 54 R <sub>x</sub>		
51 52 53 54 R <sub>x</sub>		
7.4.9 Line resistance R <sub>L</sub>	Here, the line resistance R <sub>L</sub> (2-wire circuit) is entered.	0 to Rx
7.4.10 Resistance R0	Parameter appears for setting "resistance/potentiometer" with 2, 3 or 4-wire circuit. It may be that the potentiometer cannot reach 0 $\Omega$ due to mechanical reasons. The starting resistance (e.g. left limit stop) of the potentiometer area is also entered here.	<b>0</b> to 400, 4,000 or 10,000 Ω

Parameter	Comment	Value range (default setting in bold)
7.4.11 Resistance R <sub>A</sub> , R <sub>S</sub> and R <sub>E</sub> 51 52 53 54 R <sub>A</sub> R <sub>B</sub> R <sub>B</sub>	Dependent on the setting "resistance measuring range" Here, the starting resistance of the potentiometer must be entered. I.e. the resistance (between A and S) of the sliding contact at this position (e.g. left limit stop) must be entered.	<b>0</b> to 400, 4,000 or 10,000 $\Omega$
7.4.12 Scaling start	All sensor types can be scaled here if "linear" has been entered for linearization.	-5,000 to <b>0</b> to 50,000
7.4.13 Scaling end	entered for integrization.	-5,000 to <b>100</b> to 50,000
7.4.14 Offset	With the offset, the linearized/scaled measured value can be shifted evenly by the value entered over the entire measuring range.	-5,000 to <b>0.0</b> to 50,000 °C/ °F/text
7.4.15 Fine calibration start actual	You can use the fine adjustment to correct the measured values of the analog input. This may become necessary if the scaling and offset do not result in the	
7.4.16 Fine calibration end actual	desired display.  ⇒ Figure in Chapter 5.4 "Signal flow"	-5,000 to <b>0.0</b> to 50,000
7.4.17 Fine calibration start target		-5,000 to <b>0.0</b> to 50,000
7.4.18 Fine calibration end target		-5,000 to <b>0.0</b> to 50,000
7.4.19 Noise suppression	Equalizes the input signals using the digital input filter.	Yes, No

Parameter	Comment	Value range (default setting in bold)
7.4.20 Filter time constant	Time constant of the digital input filter 2nd order If the input signal changes suddenly, approx. 26 % of the change is recorded following a period that corre- sponds to the filter time constant dF (2 × dF: approx. 59 %; 5 × dF: approx. 96 %). Value 0 means: filter switched off  If the filter time is long: - Interfering signals are better absorbed - Measured value display responds more slowly to changes	0.0 to <b>0.1</b> to 100 sec

# 7.5 Analog output

Param	eter	Comment	Value range (default setting in bold)
7.5.1	Signal type	Here, the standard signal for the analog output is set.	4 to 20 mA,
			0 to 20 mA
			2 to 10 V
			0 to 10 V
7.5.2	Output range start	Here, the output range of a temperature, resistance, current, or voltage measured value can be set (restrict-	
7.5.3	Output range end	ed). 0 to 120 °C is set in Chapter 5.4 "Signal flow".	Measuring range start to 100 to measuring range end

SIL operation

Parame	eter	Comment	Value range (default setting in bold)
7.5.4	Scaling start	Here, the output range set above is shown on the set scaling of the signal type.  2 to 8 V is set in Chapter 5.4 "Signal flow"	4 to 20 mA, (the full range of the signal type above is applied per default)
7.5.5	Scaling end		0 to <b>20</b> mA
7.5.6	Reversion output	The signal at the output can be inverted here, e.g. for a setting of 0 $^{\circ}$ C = 0 V and 50 $^{\circ}$ C = 10 V,	No, Yes
		through the reversion this becomes 50 $^{\circ}C$ = 0 V and 0 $^{\circ}C$ = 10 V at the output	
7.5.7	Error signal	If, for the measured value, the value is exceeded, not reached, or a diagnostic error occurs, the current or voltage value set on the analog output is output as a so-called error signal.	Negative signaling, positive signaling, replacement value
		For signal type 4 to 20 mA	<b>Low 3.6</b> or high 21.2 mA
		For signal type 0 to 20 mA	Low -0.4 or high 21.2 mA
		For signal type 2 to 10 V	<b>Low 1.8</b> or high 10.6 V
		For signal type 0 to 10 V	Low -0.2 or high 10.6 V
7.5.8	Response for limit error	Here you can select whether the analog output should also jump to the error value if the relay switches on "1" due to a limit value being exceeded or fallen short of.	No error signal, error signal
7.5.9	Signal from diagnosis error	Here you can select whether the device sets the analog output to an error value for all detected errors, or whether only device-relevant errors should be considered. This selection option only exists if there is a relay.	All errors, device-relevant errors

SIL operation

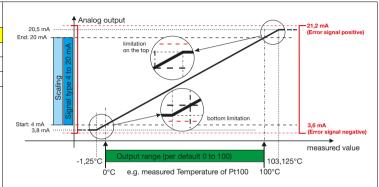
Parameter	Comment	Value range (default setting in bold)
7.5.10 Simulation output	An output current / output voltage can be simulated to test the following system. It is also possible to simulate	OFF
	residual currents/voltages.	ON
7.5.11 Simulation value	This value is simulated. The value range depends on the set signal type.	for 0(4) to 20 mA; -0.4(3.6) to 21.2 mA,
011		for 0(2) to 10 V: -0.2(1.8) to 10.6 V

SIL operation

#### 7.5.12 Behavior when leaving the scaling range

The standard signal ranges of the analog output are limited as follows according to the recommendation of NAMUR NE 43:

Lower limit	Upper limit
3.6 mA	21.2 mA
-0.4 mA	21.2 mA
1.8 V	10.6 V
-0.2 V	10.6 V
	3.6 mA -0.4 mA 1.8 V



In this example, the measured value is output from 0 to 100°C at the analog output with 4 to 20 mA.



#### Caution

The analog output is part of the safety function.

#### 7.6 Limit value monitoring

With this function, the relay output can monitor an adjustable limit value.

Depending on the set switching behavior, the relay output can switch to "1" or "0" in the event of limit value exceedance.

⇒ The limit value exceedance can also trigger a fault signal, see Chapter 7.5.8 "Response for limit error"

Parameter	Comment	Value range (default setting in bold)	
7.6.1 Function (only for relay output option)	Alarm function7 (AF7): ON electrical circuit from a fixed limit value  1 (2) (1) Limit value (2) Switching differential  Alarm function8 (AF8): OFF electrical circuit from a fixed limit value	No function AF7, AF8	
	(1) Limit value (2) Switching differential		

Parameter		Comment	Value range (default setting in bold)
7.6.2	Limit value	Here, the fixed switching point (1) is set.	Measuring range start to 0 to measuring range end in °C/°F/text
7.6.3	Switch difference	The switching differential determines the gap between the switch-on and switch-off threshold (2).	0 to 1 to 100 °C/°F/text
7.6.4	Switching behavior		standard, left, right
7.6.5	Switch on delay	The relay only switches on or off after the entered time	<b>0</b> to 9999 s
7.6.6	Switch off delay	has elapsed.	<b>0</b> to 9999 s

#### 7.7 RS485 interface

Parameter	Comment	Value range (default setting in bold)
7.7.1 Baud rate	Protocol: Modbus slave	<b>9600</b> , 19200, 38400, 57600, 115200

Param	eter	Comment	Value range (default setting in bold)
7.7.2	Data format	Data bits/stop bits/parity	8/1/no parity, 8/1/odd parity, 8/1/even parity, 8/2/no parity
7.7.3	Device address		<b>1</b> to 254

#### 7.8 Service

Param	eter	Comment	Value range (default setting in bold)
7.8.1	Minimum meas. value	Minimum measured value is displayed	
7.8.2	Maximum meas. value	Maximum measured value is displayed	
7.8.3	Min.value reset		No, Yes
7.8.4	Max.value reset		No, Yes
7.8.5	Switching cycle limit	Limit value for relay switching cycles	<b>0</b> to 29,999
		Here, the limit value for the admissible relay switching operations is set. If the counter value for <b>Current switching cycles</b> is greater than this value, the display values flash, the relay output alarm drops, and the analog output goes to the defined error value.	
		If "0" is set the function is inactive.	

#### 7 Configuration

Param	neter	Comment	Value range (default setting in bold)
7.8.6	Current switching cycles	Relay switching cycle counter	<b>0</b> to 30,000
		Here, the switching cycles for the relay are only counted if the top <b>limit value for relay switching cycles</b> is not set to "0" and is thus inactive.	
		The value can be adjusted as required and therefore adapted accordingly to the system, for example by setting it to 0 after start-up.  The switching cycle counter remains at 30,000.	

#### 8 Device info

#### 8.1 Version

Device software version channel:	Version	Version	Version	Version	: Version
Device software version diagnostics:	SW version	SW version	Serial	Check-ID	Type code
Fabrication number:	SW version channel 348.01.01	SW version channel 348.01.01	No. 0247258801	05009719	Type code SIL Yes
The first 8 digits are the production order number: 02472588 Digit 9 and 10 manufacturing site Fulda: 01 Digit 11 (second row) device version: 0 Digit 12 and 13 year: 2018 Digit 14 and 15 calendar week: 11 Digit 16 to 19 consecutive number: 0003	£09.01.01		018110003	55555115	
Inspection ID:					
Extra code SIL:					
"No" means switched off, "Yes" means switched on.					
⇒ Chapter and Chapter 10.6					

The device software version channel, device software version diagnostics, fabrication number, inspection ID and the extra code SIL are displayed here.

#### 8.2 Service

Parameter		Comment	Value range (default setting in bold)
8.2.1	Operating hours total	Operating hours counter	<b>0</b> to 99999 hours
		The counter adds up the operating hours during which the device was connected to the voltage supply.	
		The value cannot be changed and can be used as a measure of how long the device was actually in operation after leaving the factory.	
8.2.2	Operating hours since last configura-	Operation time since the last change in the configuration level	<b>0</b> to 99999 hours
	tion	Here, the time is displayed for which the device was in operation after the last time the configuration level was left. This also applies for configuration via setup program.	

#### 8.3 Hardware recognition

The extra codes installed in the device are displayed here.



#### 9 Technical data

#### 9.1 Analog input

#### 9.1.1 RTD temperature probe

Designation	Standard	Measuring range	Measuring accuracy <sup>a</sup>	R <sub>100</sub> / R <sub>0</sub>	ITS
Pt50	GOST 6651-2009 A.2			1.3911	90
2/3-wire circuit		-200 to +850 °C	±0.5 K		
4-wire circuit		-200 to +850 °C	±0.3 K		
Pt100	IEC 60751:2008			1.3851	90
2/3-wire circuit		-100 to +200 °C	±0.2 K		
		-200 to +850 °C	±0.4 K		
4-wire circuit		-100 to +200 °C	±0.1 K		
		-200 to +850 °C	±0.2 K		
Pt500, Pt1000	IEC 60751:2008			1.3851	90
2/3-wire circuit		-100 to +200 °C	±0.2 K		
		-200 to +850 °C	±0.4 K		
4-wire circuit		-100 to +200 °C	±0.1 K		
		-200 to +850 °C	±0.2 K		
Ni100, Ni500, Ni1000	DIN 43760:1987-09			1.618	IPTS-68
2/3-wire circuit		-60 to +250 °C	±0.4 K		
3-wire circuit		-60 to +250 °C	±0.2 K		
Ni100	GOST 6651-2009 A.5			1.6172	90
2/3-wire circuit		-60 to +180 °C	±0.4 K		
3-wire circuit		-60 to +180 °C	±0.2 K		

Designation	Standard	Measuring range	Measuring accuracy <sup>a</sup>	R <sub>100</sub> / R <sub>0</sub>	ITS	
Pt100 2/3-wire circuit 4-wire circuit	GOST 6651-2009 A.2	-100 to +200 °C -200 to +850 °C -100 to +200 °C -200 to +850 °C	±0.2 K ±0.4 K ±0.15 K ±0.25 K	1.3911	90	
Cu50 2/3-wire circuit 4-wire circuit	GOST 6651-2009 A.3	-180 to +200 °C -180 to +200 °C	±0.5 K ±0.3 K	1.428	90	
Cu100 2/3-wire circuit 4-wire circuit	GOST 6651-2009 A.3	-180 to +200 °C -180 to +200 °C	±0.4 K ±0.2 K	1.428	90	
Ambient temperature infl	uence	≤ ±0.005 %/K deviation from 22 °C				
Measuring current		< 0.3 mA				
Sensor line resistance		≤ 50 Ω per line for 3- and 4-wire circuit ≤ 100 ohms line resistance for 2-wire circuit				
Lead compensation		Not required for 3-wire or 4-wire circuit. In 2-wire circuits, lead compensation is performed in the software by entering a fixed line resistance.				
Special features		- Can also be programmed in °F - Basic sensor type can be changed with sensor factor (e.g., Pt50 to Pt100)			., Pt50 to	

a 
 The accuracy specifications refer to the maximum measuring range.

#### 9.1.2 Thermocouples

Designation	Standard	Measuring range	Measuring accuracy <sup>b</sup>	ITS
Fe-CuNi "L"	DIN 43710:1985-12	-200 to +900 °C	±0.1 %	68
Fe-CuNi "J"	DIN EN 60584-1:2014	-210 to +1200 °C	±0.1 % from -100 °C	90
Cu-CuNi "U"	DIN 43710:1985-12	-200 to +600 °C	±0.1 % from -100 °C	68
Cu-CuNi "T"	DIN EN 60584-1:2014	-200 to +400 °C	±0.1 % from -150 °C	90
NiCr-Ni "K"	DIN EN 60584-1:2014	-200 to +1300 °C	±0.1 % from -80 °C	90
NiCr-CuNi "E"	DIN EN 60584-1:2014	-200 to +1000 °C	±0.1 % from -80 °C	90
NiCrSi-NiSi "N"	DIN EN 60584-1:2014	-200 to +1300 °C	±0.1 % from -80 °C	90
Pt10Rh-Pt "S"	DIN EN 60584-1:2014	-50 to 1768 °C	±0.15 % from -60 °C	90
Pt13Rh-Pt "R"	DIN EN 60584-1:2014			
Pt30Rh-Pt6Rh "B"	DIN EN 60584-1:2014	-50 to 1820 °C	±0.15 % from 400 °C	90
W5Re-W26Re "C"	ASTM E230M-11	0 to 2315 °C	±0.15 %	90
W5Re-W20Re "A1"	GOST R 8.585-2001	0 to 2500 °C	±0.15 %	90
W3Re-W25Re "D"	ASTM E1751M-09	0 to 2315 °C	±0.25 %	90
Chromel®-COPEL® "L"	GOST R 8.585-2001	-200 to +800 °C	±0.1 % from -80 °C	90
Chromel®-Alumel®	GOST R 8.585-2001	-270 to +1372 °C	±0.1 % from -80 °C	90
PLII (Platinel)	ASTM E1751M-09	0 to 1395 °C	±0.15 %	90

Designation Standard	Measuring range	Measuring accuracy <sup>b</sup>	ITS		
Ambient temperature influence	$\leq \pm 0.005$ %/K deviation from 22 °C, additionally the cold junction accuracy				
Measuring range start/end	Freely programmable withi	n the limits in steps of 0.1 °C			
Cold junction	Pt1000 internal, thermostat (fixed constant value), adjustable				
Reference point accuracy (internal)	±1 K				
Reference point temperature (fixed constant value)	-20 to +80 °C adjustable				
Special features	Can also be programmed i	n °F			

b The accuracy specifications refer to the maximum measuring range.

#### 9.1.3 Standard signals

Designation	Measuring range	Measuring accuracy <sup>c</sup>	Ambient temperature influence
	DC 0 to 10 V DC 0 to 1 V 0 to 100 mV	±5 mV ±0.05 %	≤±0.005 %/K Deviation of 22 °C
Current (voltage drop ≤ 2 V), freely scalable	DC 0(4) to 20 mA	±20 μA	≤±0.005 %/K Deviation of 22 °C
Galvanic isolation	see Chapter 3.5 "Galvanische Trennung"		
Special features	Measuring range scaling, adjustable		

Designation	Measuring range	Measuring accuracy <sup>c</sup>	Ambient temperature influence
Limits in accordance with NAMUR recommendation NE 43 in case of deviation above/below measured range		Signal type 4 to 20 mA	
Measurement information M		3.8 to 20.5 mA	
Failure information A for deviation below measured value/short-circuit ("NAMUR Low")		≤ 3.6 mA	
Failure information A for deviation above measured value/probe break ("NAMUR High")		≥ 21 mA	

c The accuracy specifications refer to the maximum measuring range.

#### 9.1.4 Resistance transmitter

Designation	Measuring range	Measuring accura-	Ambient temperature influence
Resistance transmitter	max. 10 kΩ	±10 Ω	≤ ±0.01 % per K Deviation of 22 °C
Connection type	Resistance transmitter: 3-wire circuit		
Sensor line resistance	max. 50 $\Omega$ per line		
Resistance values	Freely programmable within the limits in steps of 0.1 $\Omega$		
Special features	Measuring range scaling, adjustable		

d The accuracy specifications refer to the maximum measuring range.

#### 9.1.5 Resistance/potentiometer

Designation	Measuring range	Measuring accuracy	Ambient temperature influence
Sensor type resistance/potentiometer	max. 10 kΩ	±10 Ω	≤±0.01 %/K Deviation of 22 °C
Connection type	Potentiometer with 2-, 3- or 4-wire circuit		
Sensor line resistance	$\leq$ 50 $\Omega$ per line for 3- and 4-wire circuit $\leq$ 100 $\Omega$ line resistance for 2-wire circuit		
Resistance values	Freely programmable within the limits in steps of 0.1 $\Omega$		
Special features	Measuring range scaling, adjustable		

#### 9.2 Measuring circuit monitoring

Measuring probe	Out of range	Probe/cable break	Probe/cable short circuit
RTD temperature probe	is detected	is detected	is detected
Resistance transmitter	is detected	is detected	is not detected
Thermocouple (single)	is detected	is detected	is not detected
Double thermocouple	is detected	is detected	is detected
Voltage 0 to 10 V 0 to 1 V	is detected is detected	is not detected is not detected	is not detected is not detected

Measuring probe	Out of range	Probe/cable break	Probe/cable short circuit
Current 4 to 20 mA 0 to 20 mA	is detected is detected	is detected is not detected	is detected is not detected

#### 9.3 Test voltages

Input and output against voltage supply	
- With voltage supply AC 110 to 240 V +10%, -15%	4260 V
- With voltage supply DC 24 V	4260 V

#### 9.4 Electrical safety

	Clearances / creepage distances
Mains voltage to electronic components and probes	≥ 8 mm / ≥ 4 mm
Mains voltage to relays	≥ 8 mm / ≥ 4 mm
Relays to electronic components and probes	≥ 8 mm / ≥ 4 mm

#### 9.5 Analog output

e R <sub>load</sub> Accuracy	Burden influence
≤ ±0.05% referring to 1	

#### 9.6 Relay output (extra code 018)

Designation	Function
Limit value relay output	Relay (changeover contact) Contact protection circuit: Fuse cut-out 3.15 AT installed in pin branch 30,000 switching operations at a switching capacity of AC 240 V, 3 A, 50 Hz (resistive load) or maximum DC 30 V, 3 A. Minimum current: DC 12 V, 100 mA

#### 9.7 Display

Type, resolution	Dot-matrix LCD display with 64 × 96 pixels
Brightness setting	Contrast can be adjusted on device, background lighting can be switched off via timeout

#### 9.8 Electrical data

Voltage supply	DC 24 V, +10, -15 % or AC 110 to 240 V +10, -15 %, 48 to 63 Hz
Power consumption	With voltage supply 240 V: max. 3 W, 10 VA With voltage supply 24 V: max. 3 W
Inputs and outputs Conductor cross section	Max. 2.5 mm <sup>2</sup> , wire or strand with ferrule
Electrical safety	According to DIN EN 61010-1 Overvoltage category III, pollution degree 2 Test peak voltage, measurement input to analog output: 1875 V / 50 Hz
Electromagnetic compatibility Interference emission Interference immunity	According to DIN EN 61326-1 Class A - For industrial applications only - Industrial requirements
Sampling rate	500 ms
Input filter	Digital filter, 2nd order; filter time constant can be adjusted from 0 to 100 s

#### 9.9 Environmental influences

Operating/storage temperature range	-10 to +70 °C / -20 to +80 °C
Resistance to climatic conditions	≤ 85% relative humidity, annual average, no condensation

#### 9.10 Housing

Site altitude	maximum 2000 m above MSL	
Case type, material	Plastic housing, polycarbonate (use in interiors only)	
Flammability class	UL94 V0	

Electrical connection	Pluggable screw terminals	
Mounting on	Mounting rail 35 mm x 7.5 mm according to DIN IEC 60715	
Close mounting	Permitted	
Installation position	Vertical	
Protection type	IP20 according to DIN EN 60529	
Weight with screw terminals	Approx. 200 g	

#### 9.11 Approvals/approval marks

Approval mark	Test facility	Certificate/certification number	Inspection basis	Valid for
SIL2, SIL3	TÜV Nord (German Technical Inspection Agency)	SEBS-A.093409/14 V1.0	DIN EN 61508 1-7	All modules
PLc/PLd	TÜV Nord (German Technical Inspection Agency)	SEBS-A.093409/14 V1.0	DIN EN ISO 13849	All modules
c UL us	Underwriters Laboratories	2018-10-8-E201387	UL 61010-1	All modules
DNV·GL	DNV·GL	TAA00002C4	DNVGL-CG-0339	All modules

#### 10 Setup program

The program and the connecting cable are available as accessories and offer the following possibilities:

- Easy and comfortable parameterization and archiving via PC
- Easy parameter duplication for identical types of devices

#### 10.1 Minimum hardware and software requirements:

- PC Pentium III or higher
- 200 MB free hard disk space
- CD-ROM drive
- Free USB interface, mouse connection
- Microsoft<sup>1</sup> Windows7 (32-bit) -> 1GB RAM
- Microsoft<sup>1</sup> Windows7 (64-bit) -> 2GB RAM
- \* Connect the device to the PC using the USB cable

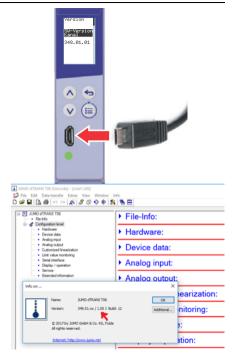
#### 10.2 Displaying the device software version

- \* Press the (E) key
- ★ Use v to switch to device info and press
- Press (a) and the software version appears.

The software versions for the device and the setup program must be compatible. Only the last two digits may be different, otherwise an error message appears!

The version of the setup prog. appears under  $Info \implies Info$  about setup.

Microsoft is a registered trademark of Microsoft Corporation



#### 10.3 Forgotten the code?

If you forget the code, it can be read out via the USB interface and the setup program.

**★** Use Data transfer ⇒ from device.



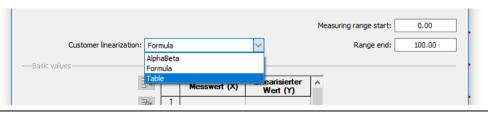
The read-out code now appears in the setup program in the sub-menu "Display/operation".

It can be kept as it is or changed.

If "0" is set and transferred to the device, the code interrogation is deactivated and the configuration level is freely accessible.

#### 10.4 Customer-specific linearization

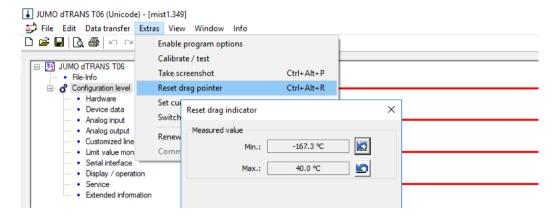
Coefficients (DKD calibration values), formulas, or 40 value pairs (grid points) can be entered in the customer linearization submenu.



#### 10.5 Reset drag indicator

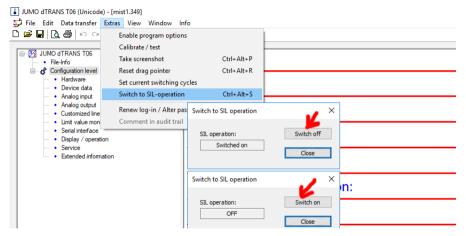
The drag indicator shows the maximum and minimum measured value. It can be reset with the setup program. The measured value currently shown in the display is set.

On the device, see Chapter 7.8.3 "Min.value reset"



#### 10.6 Switch on / switch off SIL extra code

The restrictions for SIL operation can only be deactivated with the setup program.



#### 10.7 Checking of safety relevant system settings



#### Caution

To make sure that all parameters after setup are transmitted correctly, the user has to validate the parameters, the safety function (error signal) and has to check the control action of the limit values.

#### 11 Error messages

#### 11.1 Display types

Measured value flash-	The measured value flashes.
Nesswork A	The analog output has dropped and displays the negative limit.
Rusgang:	* Press the 👆 key for further information.
-0.28	
- Find	
Error Channel: △	Here, the diagnostics channel has detected an error at the analog output, as can also be seen in the table Chapter 11.3 "Diagnostics channel".
Probe break	·
Diagnose: △	
Config. faulty	

#### 11.2 Safety channel

Display	Origin	Cause/remedy	
Terminal temperature	Internal	Terminal temperature outside the limits or probe faulty	
Reference AD converter	Internal	Deviation during the reference measurement of the AD converter/ Restart device / return device	
Not calibrated	Internal	Channel not calibrated	
Configuration	Internal	Configuration data outside the value range.	
		* Acknowledgement is not possible until it is within the admissible range again.	
CRC Test Calibr.1	Internal	Checksum error of the EEPROM calibration data.	
		Restart device / return device.	
CRC Test Config.1	Internal	Checksum error of the EEPROM configuration data.	
		Restart device / return device.	
CPU Register	Internal	A CPU registry error has occurred.	
		Restart device / return device	
RAM defective <sup>1</sup>	Internal	A RAM error has occurred.	
		Restart device / return device.	
ROM defective <sup>1</sup>	Internal	A ROM error has occurred.	
		Restart device / return device.	
Program sequence <sup>1</sup>	Internal	A program sequence error has occurred.	
		Restart device / return device.	
Watchdog <sup>1</sup>	Internal	A watchdog reset has occurred.	
		Restart device / return device.	

Display	Origin	Cause/remedy	
Voltage supply	Internal	The voltage supply is insufficient.	
		Check voltage supply.	
Frequency deviation	Internal	Error of the independent time base.	
		Restart device / return device.	
EEPROM defective	Internal	Error during internal communication with the EEPROM.	
		Restart device / return device.	
Stack	Internal	Error in the memory area reserved for the stack.	
		Restart device / return device.	
AD converter	Internal	A program sequence error has occurred.	
		Restart device / return device.	
Interrupt	Internal	Interrupt error	
		Restart device / return device.	
Limit value	System	The configured limit value has been exceeded or fallen short of.	
		Check system / adapt limit value	

#### 11.3 Diagnostics channel

Display	Origin	Cause/remedy	
Voltage 3 V	Internal device	Error detected when measuring the 3 V voltage supply Restart device / return device.	
Voltage 5 V	Internal device	Error detected when measuring the 5 V voltage supply Restart device / return device.	
Signal analog output	Internal device	Analog output signal deviates from the specification of the safety channel.  This may be caused by an "open" analog output (without load).  Note:  Error is only reported if the deviation occurs for more than 5 seconds.	
		Remedy:	
		* Check load at analog output	
		★ In the configuration level -> Service -> Reset error -> yes	
		If this error is rectified, the analog output once again delivers valid values.	
		Service   SIL =0   A restart also results in a reset of the error.   SIL =0   Measur.:   34.6     Yes   Ves   T.34     T.34	
Relay status	Internal device	Relay setting deviates from the specification of the safety channel.  Restart device / return device.	
Voltage analog output	Internal device	Error detected when measuring the analog output voltage supply. Restart device / return device.	

Display	Origin	Cause/remedy	
Software versions	Internal device	The software versions of the safety channel and diagnostics channel do not match. Restart device / return device.	
Internal comm.	Internal device	Communication between safety channel and diagnostics channel faulty. Restart device / return device.	
Editing procedure	Internal device	An error has occurred during editing. Restart device / return device.	
Relay switch cycle	Internal device	The configured limit of the switching cycles has been exceeded.	
		The error can be remedied by reducing the current counter or increasing the limit.	
		⇒ Chapter 7.8.5 "Grenze Schaltspiele"	
Config. faulty	Internal device	The configuration is faulty	
		* Check configuration	
ROM defective	Internal diagnos- tics	A ROM error has occurred. Restart device / return device.	
RAM defective	Internal diagnos- tics	A RAM error has occurred. Restart device / return device.	
Parameter faulty	Internal diagnos-	Parameter faulty	
	tics	* Check configuration	
CRC Test RAM	Internal diagnos-	CRC test of configuration in RAM returned an error	
	tics	Restart device / return device.	
CRC Test EEPROM	Internal diagnos-	CRC test of configuration in EEPROM returned an error	
	tics	Restart device / return device.	
Program sequence	Internal diagnos- tics	Program sequence faulty. Restart device / return device.	

Display	Origin	Cause/remedy
EEPROM access	Internal diagnos- tics	An error occurred during EEPROM reading/writing. Restart device / return device.
USB communication	Internal diagnos- tics	Error during communication via USB. Restart device / return device.
RS485 communication	Internal diagnos- tics	Error during RS485 communication. Restart device / return device.

#### 11.4 Measured value recording

Display	Cause/remedy			
<<<<	Underrange / check sensor configuration, check measuring chain			
>>>>	Overrange / check sensor configuration, check measuring chain			
	Invalid value / restart device, otherwise return device			
4	Division by zero / restart device, otherwise return device			
+++++	Error relating to terminal temperature or compensation signal / restart device, otherwise return device			
<-<-<	Probe short circuit / check sensor configuration, check line for short circuit			
>->->	Probe break / check sensor configuration, check line for short circuit			
-1-0-	No data received from channel / restart device, otherwise return device			
****	Value cannot be displayed, overrange / restart device, otherwise return device			

#### 12 What to do, if ...

Description	Cause	Remedy		
The following appears in the display:	Setup program transmits data. The safe state is assumed during data transmission (if SIL is active). The data is then exchanged between channel and diagnostics and then the device returns to normal state.	- Wait until data transmission has finished.		
The following appears in the display:  Check dependent parameters	Changes were made in the configuration level that are implausible or that have an impact on the downstream function blocks. This can also cause the LED to light up red. <b>Example:</b> If the sensor type is changed from RTD temperature probe to thermocouple, for example, the linearization of the thermocouple must also be entered so that the following functions such as limit value monitoring can function correctly.	Check the settings in the configuration level until the LED lights up green again.      Chapter 5.1 "Display and control elements"		

Description	Cause	Remedy		
If a parameter in this tree structure is changed, the underlying parameters	Analog input	Analog output		
must be checked for cor- rectness and adjusted if necessary.	check dependent parameters  Sensor type  Linearization  Check resistors  Measuring range  Output range  Limit value  Resistors  Rx, R0, R1	check dependent parameters Signal type  Scaling Startiend (output) Replacement value Simulation value		
Relay output limit value		* Check whether the relay option is available.		
does not switch as shown in the symbol	caused by an excessive relay current.	Measure relay terminal 21 and 22 with a continuity tester in standby mode (without voltage supply).		
	21 22 23 24	If continuity cannot be measured, the device must be repaired at JUMO.		
		⇒ For service addresses see back cover		
The backlight is off.	- Timeout lighting was activated.	* Press any key		
	The backlight switches off automatically after the set time.	or switch off timeout.		
		⇒ Chapter 7.3.5 "Time-out lighting"		

Description	Cause	Remedy		
The LED lights up red	<ul> <li>Here, all points that indicate a diagnostic error must be checked.</li> <li>Check dependent parameters (described in the table above)</li> </ul>	<ul> <li>★ Is the current output wired correctly?         The current output may not deliver current if the connected device is "too resistive" or if the cables are faulty.     </li> <li>➡ Chapter 4.2.2 "Analog output (part of the safety channel)"</li> </ul>		

#### 13 **Certificates**







TÜV NORD Systems GmbH & Co. KG hereby certifies to

JUMO GmbH & Co. KG Moritz-Juchheim-Straße 1 36039 Fulda

that the safety related temperature transmitter

# JUMO dTRANS T06 (Type 707071)

(and order detail 058) is capable for safety related applications and meet the requirements listed in the following standards.

- DIN EN 61508-1/-2/-3: 2011, SIL 2 (HFT = 0) and SIL 3 (HFT ≥ 1)
- DIN EN ISO 13849-2: 2013 DIN EN ISO 13849-1: 2016, PL c (Cat. 2, HFT = 0) and PL d (Cat. 3, HFT = 1)
- DIN EN 60730-2-9: 2011
- No. SEBS-A.093409/14TB in the valid

the pictured Safety Approved mark

Hamburg, 2018-05-18 2023-05-18

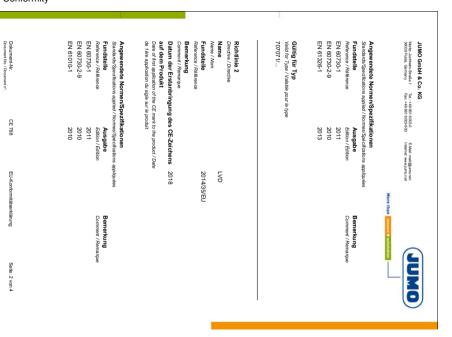




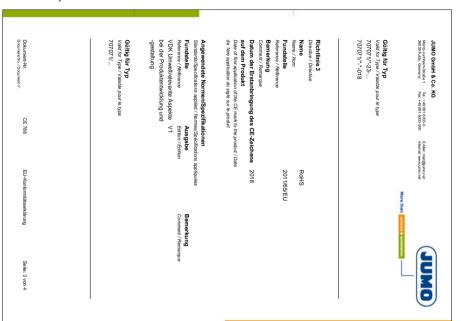
#### 13.2 EU-Conformity



#### **EU-Conformity**



#### **EU-Conformity**



#### **EU-Conformity** Dokument-Nr. Document No. / Document no Rechtsverbindliche Unterschriften Place, date / Lieu, date Ort, Datum Issued by / Etabli par Moritz-Juchheim-Straße 1 36039 Fulda, Germany JUMO GmbH & Co. KG egally binding signatures. Tel: +49 66 1 6003-0 Fax: +49 66 1 6003-500 CE 788 i. V. Harald Gienger Bereichsleiter Vertrieb Inland / Globales Produkt- und Branchenmanagement ppa. Dimitrios Charisiadis JUMO GmbH & Co. KG Fulda, 2018-04-20

#### 13.3 China RoHS



本表格依据SJ/T 11364的规定编制。

This table is prepared in accordance with the provisions SJ/T 11364.

<sup>○:</sup>表示该有害物质在该部件所有均质材料中的含量均在GB/T 26572规定的限量要求以下。

Indicate the hazardous substances in all homogeneous materials' for the part is below the limit of the GB/T 26572.

x:表示该有害物质至少在该部件的某一均质材料中的含量超出GB/T 26572规定的限量要求。
 Indicate the hazardous substances in at least one homogeneous materials of the part is exceeded the limit of the GB/T 26572.



### Street address: JUMO GmbH & Co. KG

Internet: Email: 36035 Fulda, Germany Postal address: 36039 Fulda, Germany Mackenrodtstraße 14 Delivery address: 36039 Fulda, Germany Moritz-Juchheim-Straße 1 www.jumo.net mail@jumo.net +49 661 6003-607 +49 661 6003-0

# JUMO Instrument Co. Ltd.

Harlow, Essex, CM20 2DY, UK Phone: +44 1279 63 55 33 Fax: +44 1279 62 50 29 Email: sales@jumo.co.uk Internet: www.jumo.co.uk Temple Bank, Riverway JUMO House

## 6733 Myers Road JUMO Process Control, Inc.

East Syracuse, NY 13057, USA

Email: Phone: Fax: Internet: www.jumousa.com info.us@jumo.net +1 315 437 5866 +1 315 437 5860

